

# Computation Alignment: Capacity Approximation without Noise Accumulation

Urs Niesen  
Bell Labs

Bobak Nazer  
Boston University

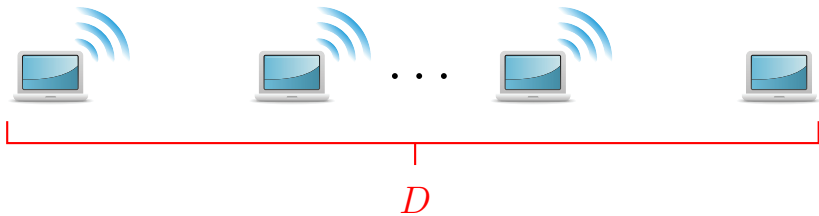
Phil Whiting  
Bell Labs

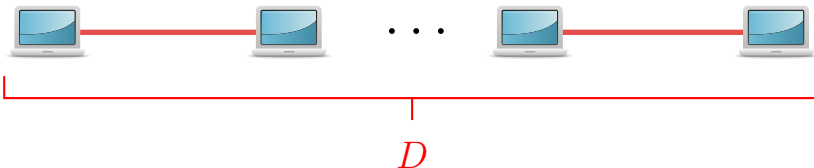
ISWCS 2011  
November 7, 2011

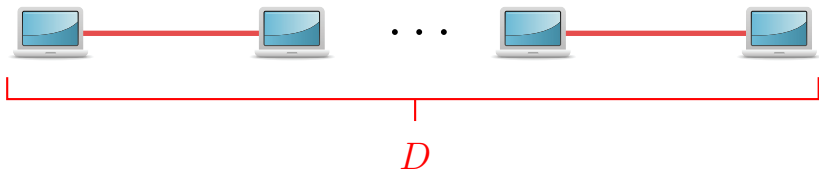


...









Capacity:  $C = \log(1 + \text{SNR})$

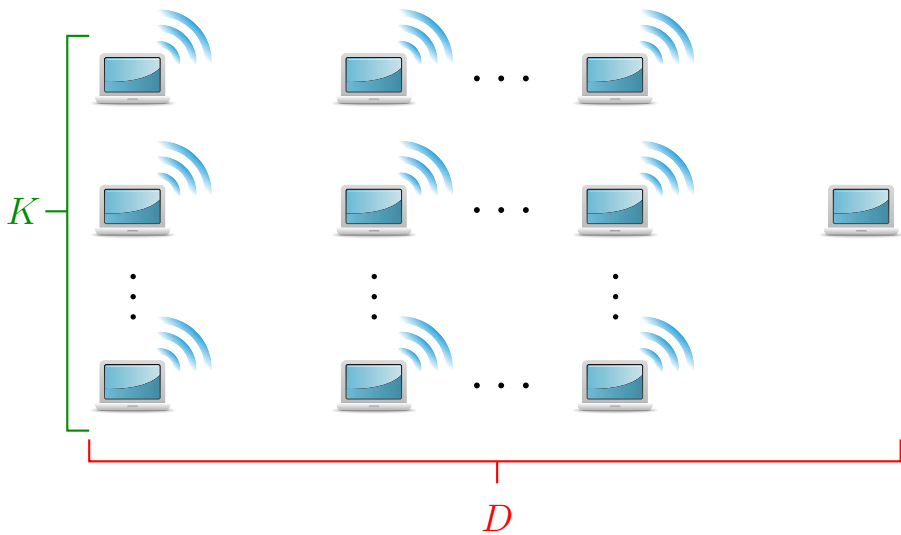


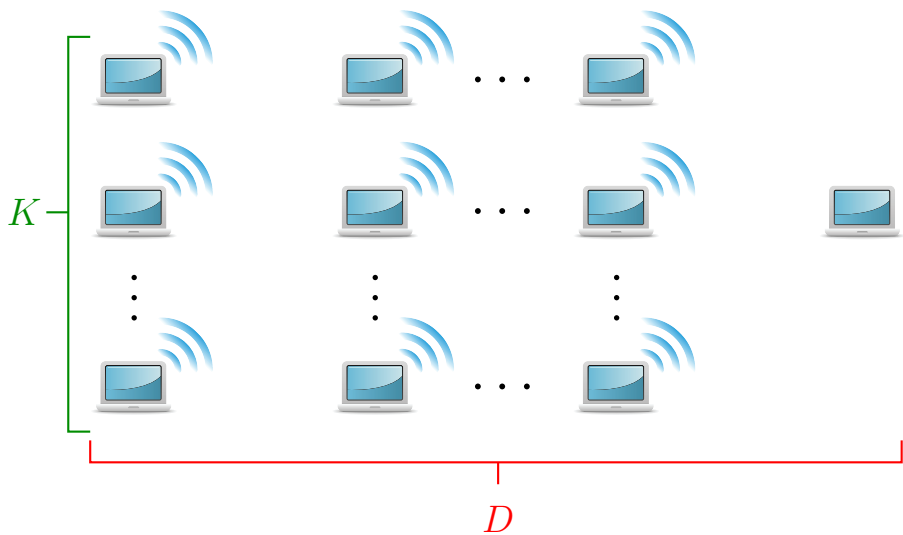
⋮

⋮

⋮







Cutset Bound:  $C \leq K \log(1 + KSNR)$



## Relaying Strategies

$K$  = Network Width

$D$  = Network Depth

- **Decode-and-Forward** (Cover-El Gamal '79): Decode subsets of messages. Removes noise but interference-limited.

$$C \geq \log(1 + KSNR)$$

## Relaying Strategies

$K$  = Network Width

$D$  = Network Depth

- **Decode-and-Forward** (Cover-El Gamal '79): Decode subsets of messages. Removes noise but interference-limited.

$$C \geq \log(1 + KSNR)$$

- **Compress-and-Forward** (Cover-El Gamal '79): Quantize analog observations. Captures signal interactions but accumulates noise.

**Avestimehr-Diggavi-Tse '11:**  $C \geq K \log(1 + KSNR) - KD$

## Relaying Strategies

$K$  = Network Width

$D$  = Network Depth

- **Decode-and-Forward** (Cover-El Gamal '79): Decode subsets of messages. Removes noise but interference-limited.

$$C \geq \log(1 + KSNR)$$

- **Compress-and-Forward** (Cover-El Gamal '79): Quantize analog observations. Captures signal interactions but accumulates noise.

Avestimehr-Diggavi-Tse '11:  $C \geq K \log(1 + KSNR) - KD$

- **Compute-and-Forward** (Nazer-Gastpar '11): Decode equations of messages. Partially captures signal interactions and removes noise.

What rates are attainable?

## Compute-and-Forward to a Single Relay

Finite field messages:

$$\mathbf{w}_\ell \in \mathbb{F}_q^m$$

Power-constrained inputs:

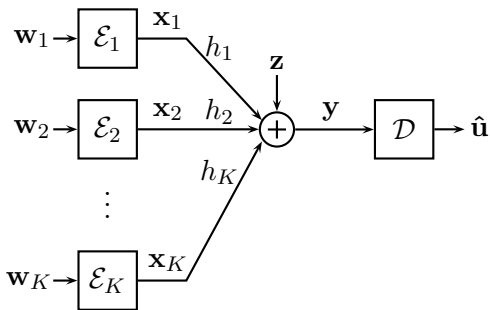
$$\frac{1}{n} \|\mathbf{x}_\ell\|^2 \leq \text{SNR}$$

AWGN noise:

$$\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

Message rate:

$$R_\ell = \frac{m}{n} \log_2 q$$

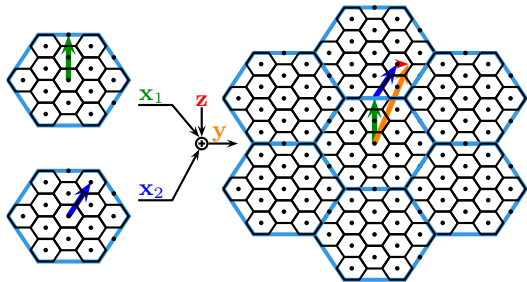


- Decoder makes an estimate  $\hat{\mathbf{u}}$  of a **linear equation**  $\mathbf{u} = \bigoplus_{\ell=1}^K a_\ell \mathbf{w}_\ell$
- Require that probability of error vanishes with blocklength.
- Receiver can use its knowledge of the channel gains to match the integer equation coefficients  $a_\ell$  to the channel coefficients  $h_\ell$ .

## Compute-and-Forward – Single Receiver

Lattice codes: Sums of codewords are codewords.

Erez-Zamir '04: Nested lattice codes can approach AWGN capacity.



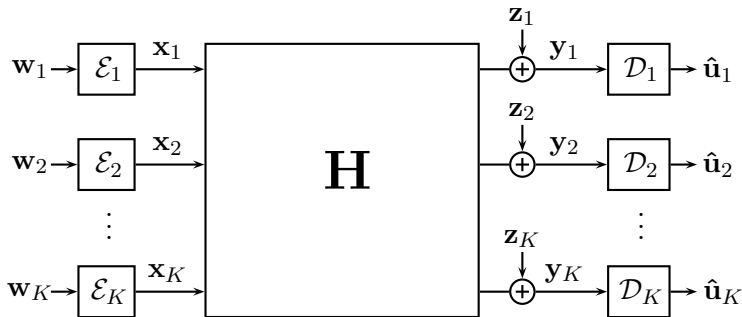
### Theorem (Nazer-Gastpar IT Trans. '11)

A relay can reliably decode the linear equation with coefficients  $\mathbf{a} \in \mathbb{Z}^K$  from a channel with coefficients  $\mathbf{h} \in \mathbb{R}^K$  if the message rates satisfy:

$$R_\ell < \max_{\alpha \in \mathbb{R}} \frac{1}{2} \log \left( \frac{\text{SNR}}{|\alpha|^2 + \text{SNR} \|\alpha \mathbf{h} - \mathbf{a}\|^2} \right)$$

For complex-valued channels, use real-valued decomposition.

## Compute-and-Forward – Multiple Receivers



### Theorem (Nazer-Gastpar IT Trans. '11)

The relays can decode a full rank set of linear equations from a channel matrix with rows  $\mathbf{h}_k^T \in \mathbb{C}^K$  as long as for some full rank matrix with columns  $\mathbf{a}_k \in \{\mathbb{Z} + j\mathbb{Z}\}^K$  the message rates satisfy:

$$R_\ell < \min_{k: a_{k\ell} \neq 0} \log \left( \frac{1 + \text{SNR} \|\mathbf{h}_k\|^2}{\|\mathbf{a}_k\|^2 + \text{SNR} (\|\mathbf{h}_k\|^2 \|\mathbf{a}_k\|^2 - (\mathbf{h}_k^* \mathbf{a}_k)^2)} \right)$$

## Compute-and-Forward – Degrees-of-Freedom

- Compute-and-forward performs well in simulations at moderate SNR (e.g. 15dB). Does it scale like  $K \log \text{SNR}$ ?

## *Compute-and-Forward – Degrees-of-Freedom*

- Compute-and-forward performs well in simulations at moderate SNR (e.g. 15dB). Does it scale like  $K \log \text{SNR}$ ?

### **Theorem (Niesen-Whiting ISIT '11, arXiv '11)**

*Compute-and-forward scheme from Nazer-Gastpar '11 has at most 2 degrees-of-freedom.*



## Compute-and-Forward – Degrees-of-Freedom

- Compute-and-forward performs well in simulations at moderate SNR (e.g. 15dB). Does it scale like  $K \log \text{SNR}$ ?

### **Theorem (Niesen-Whiting ISIT '11, arXiv '11)**

*Compute-and-forward scheme from Nazer-Gastpar '11 has at most 2 degrees-of-freedom.*

- Is that the end of the story?

## Compute-and-Forward – Degrees-of-Freedom

- Compute-and-forward performs well in simulations at moderate SNR (e.g. 15dB). Does it scale like  $K \log \text{SNR}$ ?

### Theorem (Niesen-Whiting ISIT '11, arXiv '11)

*Compute-and-forward scheme from Nazer-Gastpar '11 has at most 2 degrees-of-freedom.*

- Is that the end of the story?

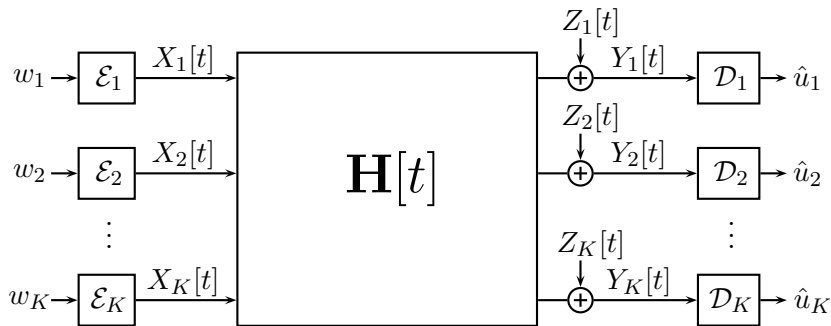
### Theorem (Niesen-Whiting ISIT '11, arXiv '11)

*Coupling compute-and-forward with interference alignment can achieve  $K$  degrees-of-freedom.*

- **Key Idea:** Use alignment scheme from **Motahari et al. '09** to create effective integer channels that are good for compute-and-forward.

- In the high SNR limit, **noise accumulation** does not show up: we could just as well use compress-and-forward.
- **Goal for this talk:** Design a **computation alignment** scheme that can send equations with rates within a constant gap of  $K \log \text{SNR}$ .
- **Ergodic interference alignment** schemes offer excellent finite SNR rates for the standard interference channel problem.
- Requires time-varying channel coefficients. Our constant gap will depend on the **number of sources**  $K$  and the **fading statistics** but not the **network depth**  $D$ .

## Computation Alignment - Setup



- Relays recover an invertible set of functions

$$u_k = f_k(w_1, w_2, \dots, w_K)$$

- Vanishing probability of error.
- Channel coefficients are independent from each other, stationary and ergodic across time, and have **uniform phase**.

### Basic ergodic alignment scheme:

- Assume each relay wants a single message,  $u_k = w_k$ .
- **Nazer-Gastpar-Jafar-Vishwanath '09:** The following rate is achievable for each user:

$$R_k = \frac{1}{2} \mathbb{E} [\log(1 + 2|h_{kk}|^2 \text{SNR})]$$

- Corresponds to a sum rate that scales like  $\frac{K}{2} \log \text{SNR}$ .

## Starting Point – Ergodic Interference Alignment

1. At time  $t$  with channel  $\mathbf{H}$ , user  $k$  transmits symbol  $X_k$ .

$$\mathbf{H} = \begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1K} \\ h_{21} & h_{22} & \cdots & h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ h_{K1} & h_{K2} & \cdots & h_{KK} \end{bmatrix}$$

## Starting Point – Ergodic Interference Alignment

1. At time  $t$  with channel  $\mathbf{H}$ , user  $k$  transmits symbol  $X_k$ .

$$\mathbf{H} = \begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1K} \\ h_{21} & h_{22} & \cdots & h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ h_{K1} & h_{K2} & \cdots & h_{KK} \end{bmatrix}$$

2. When complementary matrix  $\mathbf{H}_C$  occurs, retransmit symbol  $X_k$ .

$$\mathbf{H}_C = \begin{bmatrix} h_{11} & -h_{12} & \cdots & -h_{1K} \\ -h_{21} & h_{22} & \cdots & -h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ -h_{K1} & -h_{K2} & \cdots & h_{KK} \end{bmatrix}$$

## Starting Point – Ergodic Interference Alignment

1. At time  $t$  with channel  $\mathbf{H}$ , user  $k$  transmits symbol  $X_k$ .

$$\mathbf{H} = \begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1K} \\ h_{21} & h_{22} & \cdots & h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ h_{K1} & h_{K2} & \cdots & h_{KK} \end{bmatrix}$$

2. When complementary matrix  $\mathbf{H}_C$  occurs, retransmit symbol  $X_k$ .

$$\mathbf{H}_C = \begin{bmatrix} h_{11} & -h_{12} & \cdots & -h_{1K} \\ -h_{21} & h_{22} & \cdots & -h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ -h_{K1} & -h_{K2} & \cdots & h_{KK} \end{bmatrix} \pm \delta$$



## Starting Point – Ergodic Interference Alignment

1. At time  $t$  with channel  $\mathbf{H}$ , user  $k$  transmits symbol  $X_k$ .

$$\mathbf{H} = \begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1K} \\ h_{21} & h_{22} & \cdots & h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ h_{K1} & h_{K2} & \cdots & h_{KK} \end{bmatrix}$$

2. When complementary matrix  $\mathbf{H}_C$  occurs, retransmit symbol  $X_k$ .

$$\mathbf{H}_C = \begin{bmatrix} h_{11} & -h_{12} & \cdots & -h_{1K} \\ -h_{21} & h_{22} & \cdots & -h_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ -h_{K1} & -h_{K2} & \cdots & h_{KK} \end{bmatrix} \pm \delta$$

3. Otherwise, transmit new symbols and wait for their  $\mathbf{H}_C$ .

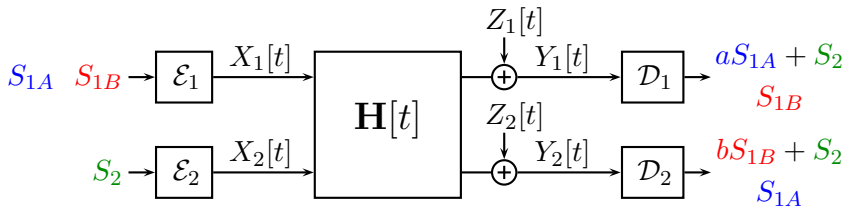
## Starting Point – Ergodic Interference Alignment

- For long block lengths, **nearly every** matrix finds its quantized match.
- In general, we can successfully pair together matrices if their coefficients are **phase rotations** of each other,

$$h_{kl}[t_C] = e^{j\phi_{kl}} h_{kl}[t] .$$

- **Computation alignment:** Pair up coefficients to create effective integer channels.

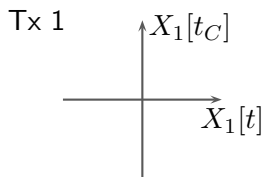
## Computation Alignment - Motivating Example



- Send 3 symbols over 2 channel uses. Sum rate is:

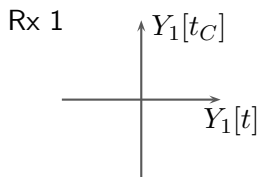
$$R_{\text{sum}} = \frac{3}{2} \mathbb{E} \left[ \min_{k,\ell} \log(1 + |h_{k\ell}|^2 \text{SNR}) \right]$$

- Each relay gets 2 equations. Coefficients  $a$  and  $b$  are non-zero integers so equations are always invertible.
- Use compute-and-forward to code over resulting effective channels.



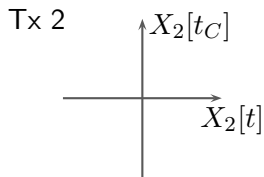
$$X_1[t] =$$

$$X_1[t_C] =$$



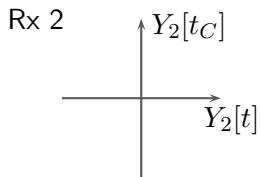
$$Y_1[t] + Y_1[t_C] =$$

$$Y_1[t] - Y_1[t_C] =$$



$$X_2[t] =$$

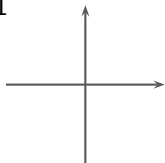
$$X_2[t_C] =$$



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

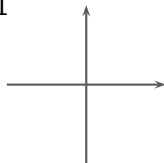
Tx 1



$$X_1[t] =$$

$$X_1[t_C] =$$

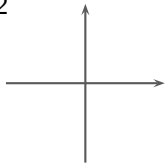
Rx 1



$$Y_1[t] + Y_1[t_C] =$$

$$Y_1[t] - Y_1[t_C] =$$

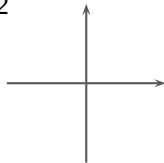
Tx 2



$$X_2[t] =$$

$$X_2[t_C] =$$

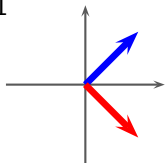
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

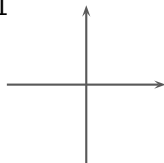
Tx 1



$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

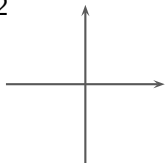
Rx 1



$$Y_1[t] + Y_1[t_C] =$$

$$Y_1[t] - Y_1[t_C] =$$

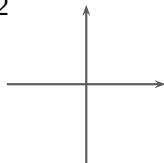
Tx 2



$$X_2[t] =$$

$$X_2[t_C] =$$

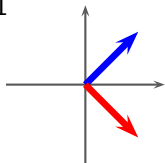
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

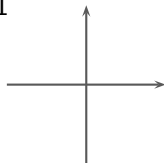
Tx 1



$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

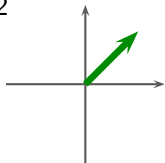
Rx 1



$$Y_1[t] + Y_1[t_C] =$$

$$Y_1[t] - Y_1[t_C] =$$

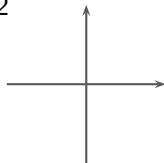
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

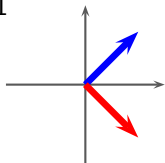
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

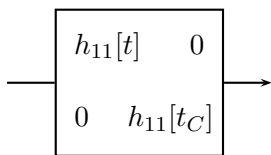
Tx 1



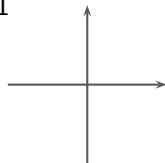
$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

Channel Gains



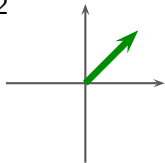
Rx 1



$$Y_1[t] + Y_1[t_C] =$$

$$Y_1[t] - Y_1[t_C] =$$

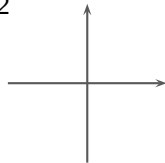
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

Rx 2

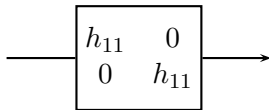
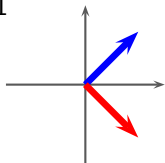


$$Y_2[t] + Y_2[t_C] =$$

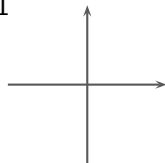
$$Y_2[t] - Y_2[t_C] =$$



Tx 1



Rx 1



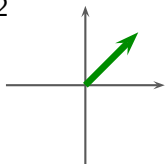
$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

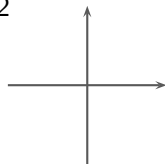
$$Y_1[t] + Y_1[t_C] =$$

$$Y_1[t] - Y_1[t_C] =$$

Tx 2



Rx 2



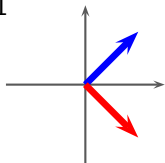
$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

$$Y_2[t] + Y_2[t_C] =$$

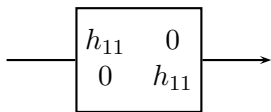
$$Y_2[t] - Y_2[t_C] =$$

Tx 1

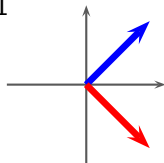


$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$



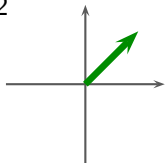
Rx 1



$$Y_1[t] + Y_1[t_C] = 2h_{11}S_{1A}$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

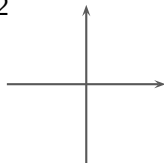
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

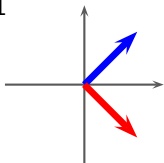
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

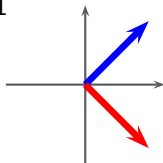
Tx 1



$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

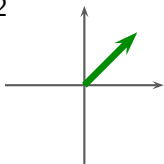
Rx 1



$$Y_1[t] + Y_1[t_C] = 2h_{11}S_{1A}$$

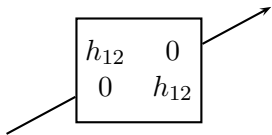
$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Tx 2

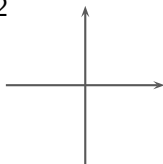


$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$



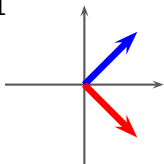
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

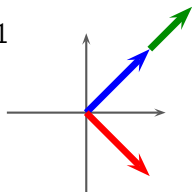
Tx 1



$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

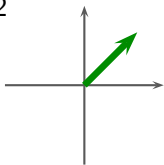
Rx 1



$$Y_1[t] + Y_1[t_C] = 2(h_{11}S_{1A} + h_{12}S_2)$$

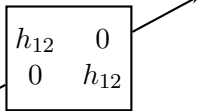
$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Tx 2

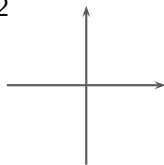


$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$



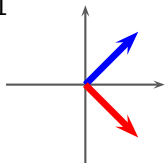
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

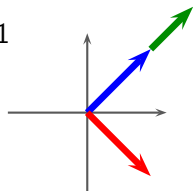
$$Y_2[t] - Y_2[t_C] =$$

Tx 1



Adjust strength of  $S_{1A}$   
to get integer coefficients.

Rx 1



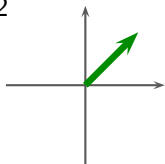
$$X_1[t] = S_{1A} + S_{1B}$$

$$X_1[t_C] = S_{1A} - S_{1B}$$

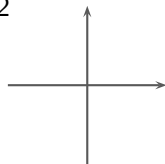
$$Y_1[t] + Y_1[t_C] = 2(h_{11}S_{1A} + h_{12}S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Tx 2



Rx 2



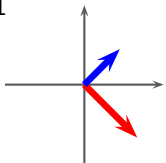
$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

$$Y_2[t] + Y_2[t_C] =$$

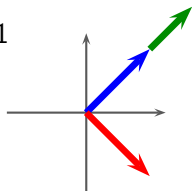
$$Y_2[t] - Y_2[t_C] =$$

Tx 1



Adjust strength of  $S_{1A}$   
to get integer coefficients.

Rx 1



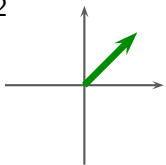
$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

$$Y_1[t] + Y_1[t_C] = 2(h_{11} S_{1A} + h_{12} S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11} S_{1B}$$

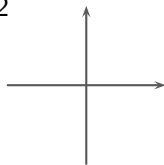
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

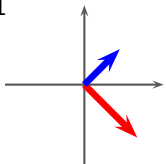
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

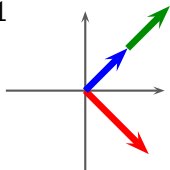
$$Y_2[t] - Y_2[t_C] =$$

Tx 1



Adjust strength of  $S_{1A}$   
to get integer coefficients.

Rx 1



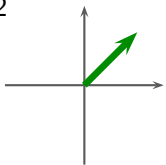
$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

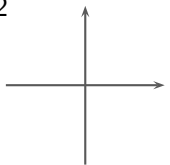
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

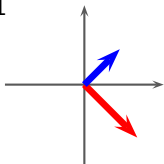
Rx 2



$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

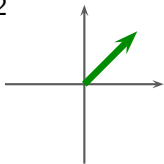
Tx 1



$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

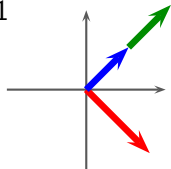
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

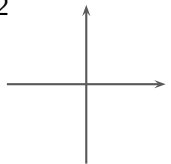
Rx 1



$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Rx 2



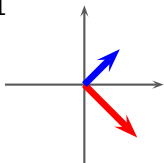
$$Y_2[t] + Y_2[t_C] =$$

$$Y_2[t] - Y_2[t_C] =$$

$h_{21}$	$0$
$0$	$-h_{21}$



Tx 1

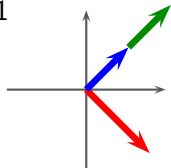


$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

$$\begin{bmatrix} h_{21} & 0 \\ 0 & -h_{21} \end{bmatrix}$$

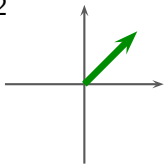
Rx 1



$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

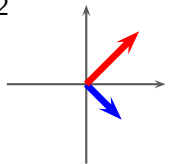
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

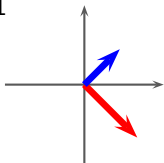
Rx 2



$$Y_2[t] + Y_2[t_C] = 2h_{21}S_{1B}$$

$$Y_2[t] - Y_2[t_C] = 2h_{21}\rho S_{1A}$$

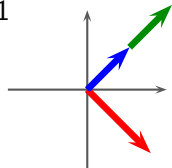
Tx 1



$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

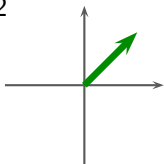
Rx 1



$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

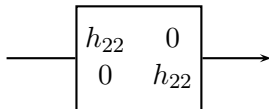
$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Tx 2

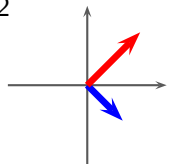


$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$



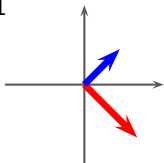
Rx 2



$$Y_2[t] + Y_2[t_C] = 2h_{21}S_{1B}$$

$$Y_2[t] - Y_2[t_C] = 2h_{21}\rho S_{1A}$$

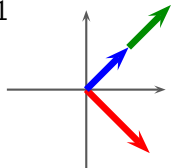
Tx 1



$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

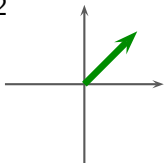
Rx 1



$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

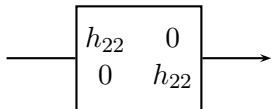
$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Tx 2

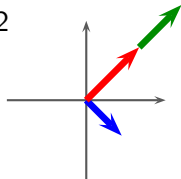


$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$



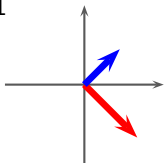
Rx 2



$$Y_2[t] + Y_2[t_C] = 2(h_{21}S_{1B} + h_{22}S_2)$$

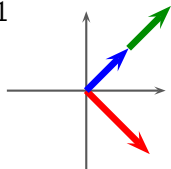
$$Y_2[t] - Y_2[t_C] = 2h_{21}\rho S_{1A}$$

Tx 1



Adjust strength of  $S_{1B}$   
to get integer coefficients.

Rx 1



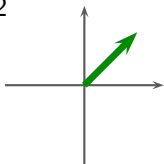
$$X_1[t] = \rho S_{1A} + S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - S_{1B}$$

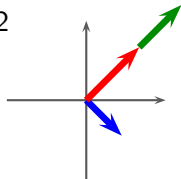
$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

Tx 2



Rx 2



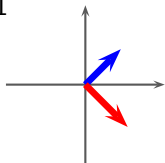
$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

$$Y_2[t] + Y_2[t_C] = 2(h_{21}S_{1B} + h_{22}S_2)$$

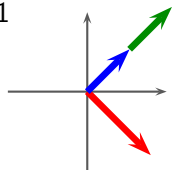
$$Y_2[t] - Y_2[t_C] = 2h_{21}\rho S_{1A}$$

Tx 1



Adjust strength of  $S_{1B}$   
to get integer coefficients.

Rx 1



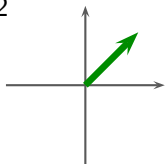
$$X_1[t] = \rho S_{1A} + \gamma S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - \gamma S_{1B}$$

$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}S_{1B}$$

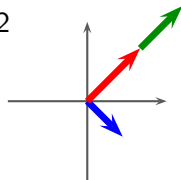
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

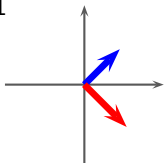
Rx 2



$$Y_2[t] + Y_2[t_C] = 2(h_{21}S_{1B} + h_{22}S_2)$$

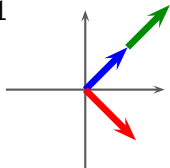
$$Y_2[t] - Y_2[t_C] = 2h_{21}\rho S_{1A}$$

Tx 1



Adjust strength of  $S_{1B}$   
to get integer coefficients.

Rx 1



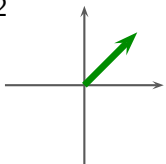
$$X_1[t] = \rho S_{1A} + \gamma S_{1B}$$

$$X_1[t_C] = \rho S_{1A} - \gamma S_{1B}$$

$$Y_1[t] + Y_1[t_C] = 2h_{12}(aS_{1A} + S_2)$$

$$Y_1[t] - Y_1[t_C] = 2h_{11}\gamma S_{1B}$$

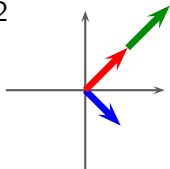
Tx 2



$$X_2[t] = S_2$$

$$X_2[t_C] = S_2$$

Rx 2



$$Y_2[t] + Y_2[t_C] = 2h_{22}(bS_{1B} + S_2)$$

$$Y_2[t] - Y_2[t_C] = 2h_{21}\rho S_{1A}$$

## Computation Alignment - Main Result

$K = 2$  case:

- User 1 sends  $L$  symbols using  $L$  DFT vectors.
- User 2 sends  $L - 1$  symbols using  $L - 1$  DFT vectors.
- Relays get  $2L$  equations. Sum rate is approximately  $\frac{2L-1}{L} \log \text{SNR}$ .

## Computation Alignment - Main Result

$K = 2$  case:

- User 1 sends  $L$  symbols using  $L$  DFT vectors.
- User 2 sends  $L - 1$  symbols using  $L - 1$  DFT vectors.
- Relays get  $2L$  equations. Sum rate is approximately  $\frac{2L-1}{L} \log \text{SNR}$ .

$K \geq 2$  case: More sophisticated set of alignment vectors.

### Theorem (Niesen-Nazer-Whiting arXiv '11)

For Rayleigh fading,  $h_{k\ell}[t] \sim \mathcal{CN}(0, 1)$ , the following sum rate is achievable using computation alignment:

$$R_{sum} = K \log \text{SNR} - 7K^3 .$$



## Computation Alignment - Main Result

$K = 2$  case:

- User 1 sends  $L$  symbols using  $L$  DFT vectors.
- User 2 sends  $L - 1$  symbols using  $L - 1$  DFT vectors.
- Relays get  $2L$  equations. Sum rate is approximately  $\frac{2L-1}{L} \log \text{SNR}$ .

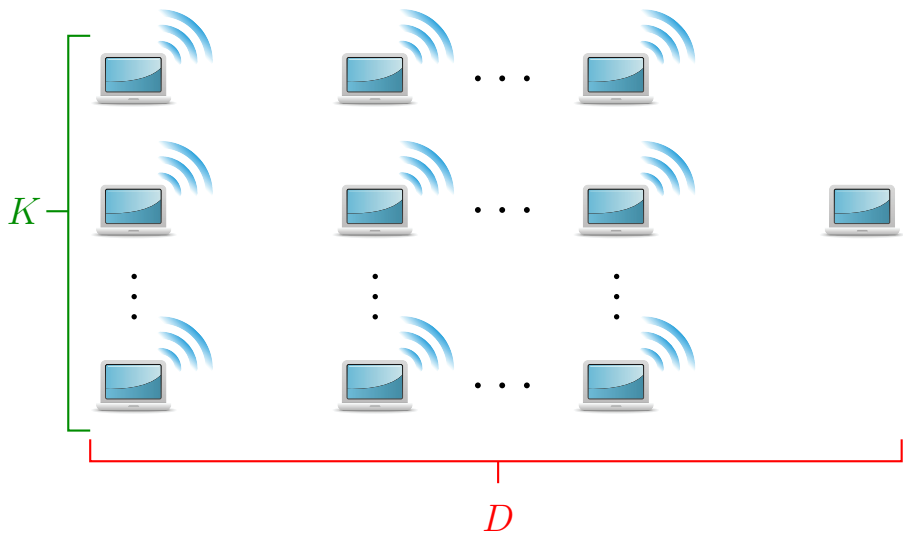
$K \geq 2$  case: More sophisticated set of alignment vectors.

### Theorem (Niesen-Nazer-Whiting arXiv '11)

For Rayleigh fading,  $h_{k\ell}[t] \sim \mathcal{CN}(0, 1)$ , the following sum rate is achievable using computation alignment:

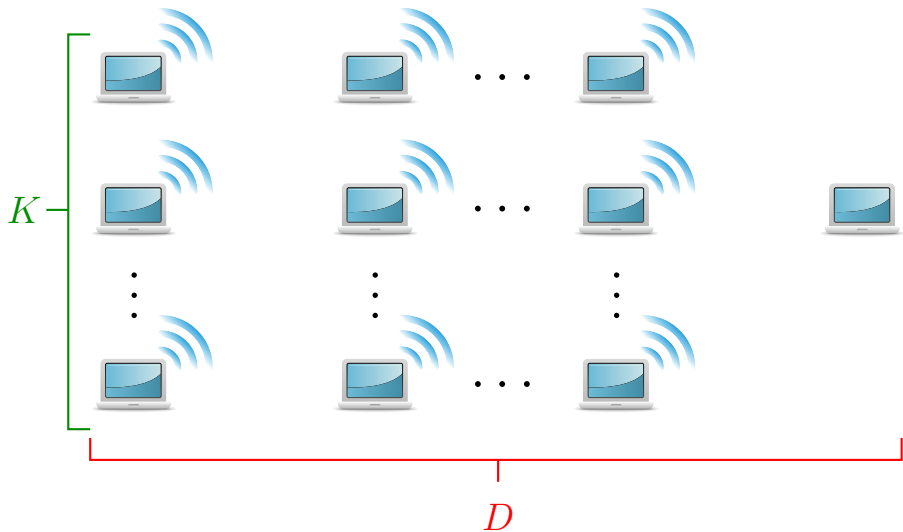
$$R_{\text{sum}} = K \log \text{SNR} - 7K^3 .$$

- Penalty term is due to setting rates using the **weakest coefficient**.
- For **equal magnitudes**,  $|h_{k\ell}| = 1$ , we can achieve  $R_{\text{sum}} = K \log \text{SNR}$ .



**Avestimehr-Diggavi-Tse '11:**  $C \geq K \log \text{SNR} - g_1(K, D)$

**This talk:**  $C \geq K \log \text{SNR} - g_2(K, \text{fading})$



**Avestimehr-Diggavi-Tse '11:**  $C \geq K \log \text{SNR} - KD$

**This talk:**  $C \geq K \log \text{SNR} - 7K^3$

## Conclusions and Future Work

- **Compute-and-forward** combined with **alignment** as a new tool for capacity approximation.
- More work is needed to get a constant gap that **does not** depend on the fading statistics.
- Multiple receivers. Layered interference channels.
- Fixed channel coefficients.
- For more info: ISIT '11 tutorial slides on Algebraic Structure in Network Information Theory available at [iss.bu.edu/bobak](http://iss.bu.edu/bobak)