

Axiomatic Theory of Probability

- The basic model for probability starts with:
 - An **experiment** which is a procedure for generating observable outcomes.
 - An **outcome** is a possible observation from an experiment. We use the notation w for an outcome.
 - A **sample space** Ω , which is the set of all possible outcomes
- An **event** is a subset of Ω : it is a collection of possible outcomes.

- Example 1:

Experiment: Roll a six-sided die once.

Outcome: A number $\omega = 1, 2, 3, 4, 5, 6$

Sample Space: $\Omega = \{1, 2, 3, 4, 5, 6\}$

Possible Events: $E_1 = \{\text{roll is odd}\} = \{1, 3, 5\}$

$E_2 = \{\text{roll is less than } 3\} = \{1, 2\}$

- Example 2:

Experiment: Two consecutive rolls of a four-sided die (order matters).

Outcomes: A pair $\omega = (i, j)$ where $i, j \in \{1, 2, 3, 4\}$

Sample Space: 16 distinct pairs

$$\Omega = \{(i, j) : i, j \in \{1, 2, 3, 4\}\}$$

$$= \{(1, 1), \dots, (1, 4), \dots, (4, 1), \dots, (4, 4)\}$$

Possible Events: $E_1 = \{\text{sum of rolls is } 4\} = \{(1, 3), (2, 2), (3, 1)\}$

$E_2 = \{\text{rolls equal}\} = \{(1, 1), (2, 2), (3, 3), (4, 4)\}$

- Example 3:

Experiment: Go to St. Mary's Green Line Station and wait for an inbound train. Record the time you wait in minutes (including decimals).

Outcome: a non-negative number w .

Sample Space: $\Omega = [0, \infty)$

Possible Events: $E_1 = \{ \text{train arrives in under two and a half minutes} \}$

$$= [0, 2.5)$$

$E_2 = \{ \text{train takes more than twenty minutes} \}$

$$= (20, \infty)$$

- The event space \mathcal{E} is a collection of subsets of the sample space Ω , chosen so that
 - \mathcal{E} contains the sample space, $\Omega \in \mathcal{E}$
 - \mathcal{E} is closed under complements, $A \in \mathcal{E} \Rightarrow A^c \in \mathcal{E}$
 - \mathcal{E} is closed under countable unions,
 $A_1, A_2, \dots \in \mathcal{E} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{E}$
- We will only work with events from the event space.
 - This will be constructed for us, no need to worry about it.

Probability Axioms

- The probability measure \mathbb{P} assigns probability values from $[0,1]$ to every event in the event space \mathcal{E} . It satisfies the following axioms:

① For any event $A \in \mathcal{E}$, $\mathbb{P}[A] \geq 0$. (Non-negativity)

② $\mathbb{P}[\Omega] = 1$ (Normalization)

(Countable Additivity)

③ For any countable collection A_1, A_2, \dots of mutually exclusive events, $\mathbb{P}[A_1 \cup A_2 \cup \dots] = \mathbb{P}[A_1] + \mathbb{P}[A_2] + \dots$

(Can also write this as $\mathbb{P}\left[\bigcup_{i=1}^{\infty} A_i\right] = \sum_{i=1}^{\infty} \mathbb{P}[A_i]$)

- Basic intuition for probabilities:

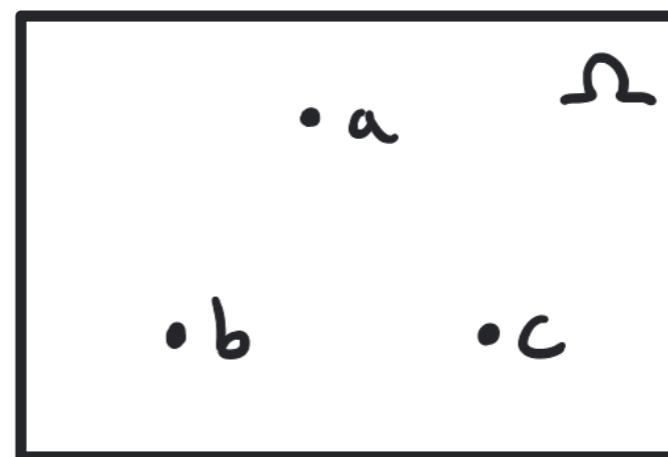
→ $\text{IP}[A] = 0$ means the event A never occurs.

→ $\text{IP}[A] = 1$ means the event A always occurs.

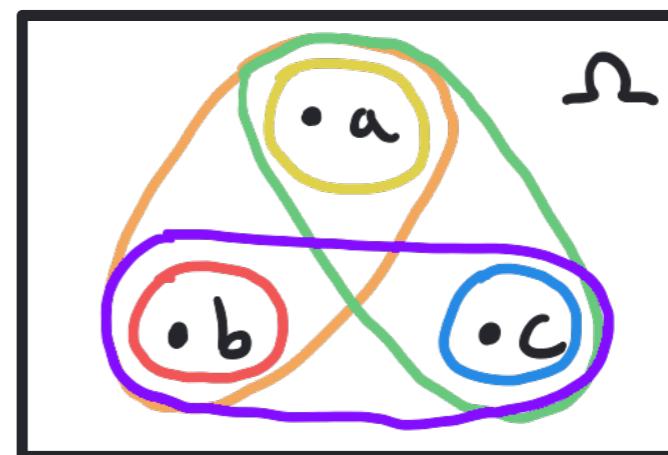
→ $0 < \text{IP}[A] < 1$ means the event A sometimes occurs.

Higher values of $\text{IP}[A]$ correspond proportionally to higher likelihood of occurrence.

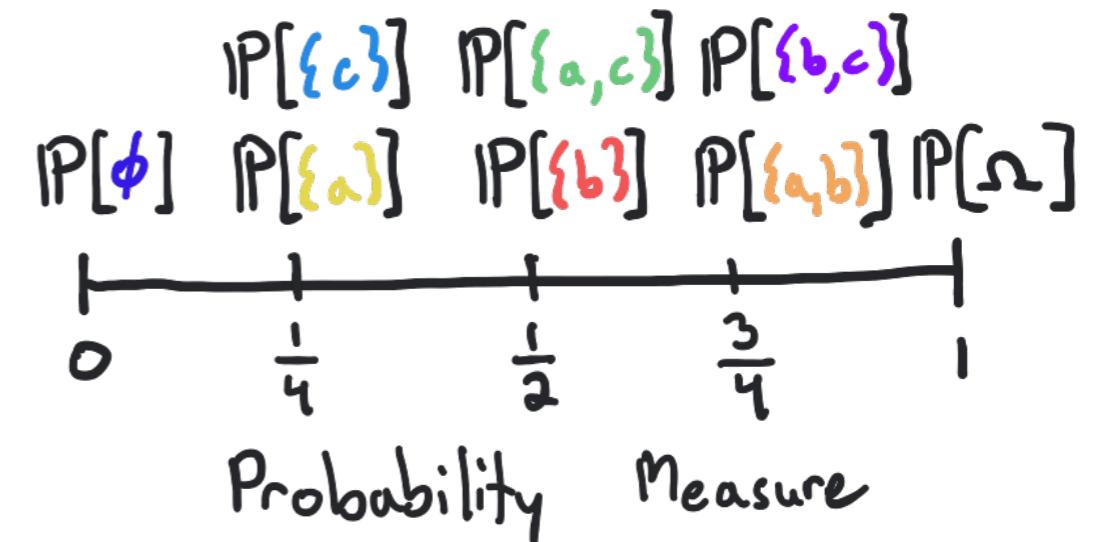
- A probability space $(\Omega, \mathcal{E}, \mathbb{P})$ consists of a
 - sample space Ω , which is the set of possible outcomes
 - event space \mathcal{E} , which is the set of possible events, each of which is a subset of Ω
 - probability measure \mathbb{P} , which assigns a probability between 0 and 1 to each event in \mathcal{E}



Sample Space

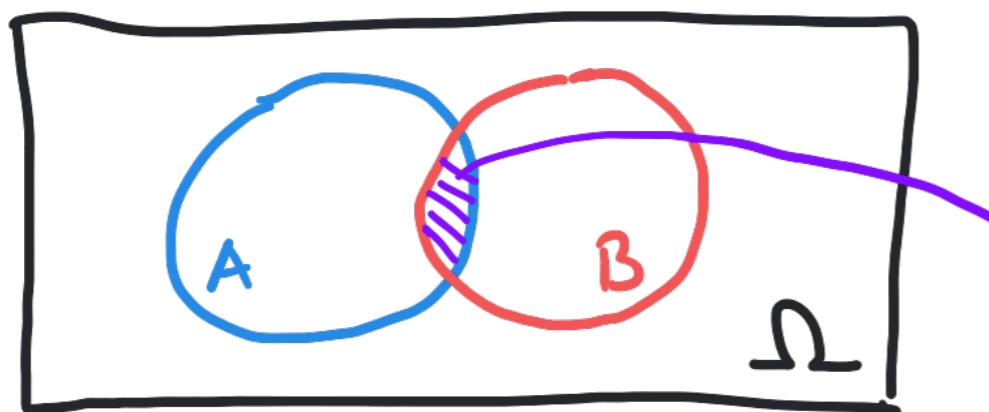


Event Space
 \emptyset



Basic Probability Properties

- For any finite collection A_1, A_2, \dots, A_n of mutually exclusive events, $P\left[\bigcup_{i=1}^n A_i\right] = \sum_{i=1}^n P[A_i]$.
→ For two mutually exclusive events A, B ,
 $P[A \cup B] = P[A] + P[B]$.
- $P[\emptyset] = 0$.
- For any event A , $P[A^c] = 1 - P[A]$. (Complement)
- For any events A, B , $P[A \cup B] = P[A] + P[B] - P[A \cap B]$



(Inclusion - Exclusion)

$P[A] + P[B]$ counts the intersection probability $P[A \cap B]$ twice.

- Back to Example 1: Roll a six-sided die. $\Omega = \{1, 2, 3, 4, 5, 6\}$

Assume outcomes are equally likely: $P[\{1\}] = \dots = P[\{6\}] = \alpha$

$$\rightarrow \text{Solve for } \alpha. \text{ We know that } \sum_{\omega=1}^6 P[\{\omega\}] = P[\Omega] = 1$$

additivity normalization

$$\text{Therefore, } \sum_{\omega=1}^6 P[\{\omega\}] = \sum_{\omega=1}^6 \alpha = 1 \Rightarrow 6\alpha = 1 \Rightarrow \alpha = \frac{1}{6}$$

- What is the probability the roll is odd?

$$\begin{aligned} P[\{\text{roll is odd}\}] &= P[E_1] = P[\{1, 3, 5\}] = P[\{1\}] + P[\{3\}] + P[\{5\}] \\ &= \frac{1}{6} + \frac{1}{6} + \frac{1}{6} = \frac{1}{2} \end{aligned}$$

- What is the probability the roll is less than 3?

$$P[\{\text{less than 3}\}] = P[E_2] = P[\{1, 2\}] = P[\{1\}] + P[\{2\}] = \frac{1}{6} + \frac{1}{6} = \frac{1}{3}$$

- What is the probability the roll is odd **and/or** less than 3?

$$P[E_1 \cap E_2] = P[\{1\}] = \frac{1}{6} \quad P[E_1 \cup E_2] = P[\{1, 2, 3, 5\}] = \frac{4}{6} = \frac{2}{3}$$

Alternatively, by Inclusion - Exclusion,

$$\begin{aligned} P[E_1] + P[E_2] - P[E_1 \cap E_2] \\ = \frac{1}{2} + \frac{1}{3} - \frac{1}{6} = \frac{2}{3} \end{aligned}$$

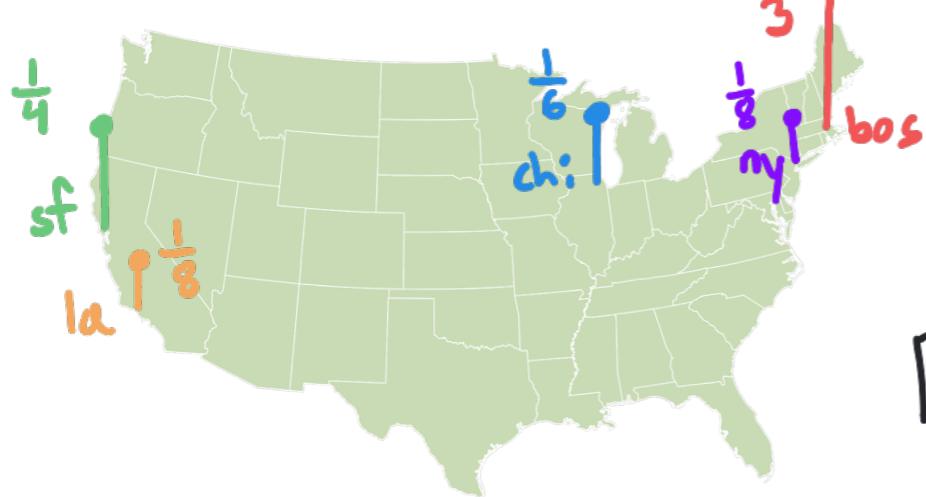
- If a sample space Ω consists of a finite number of outcomes, we can simply take the event space \mathcal{E} to be all possible subsets of Ω and construct the probability measure P by assigning probabilities to outcomes.

- Ex: Experiment: Ask a stranger which city they prefer:
Boston, Chicago, Los Angeles, New York, San Francisco

Sample Space: $\Omega = \{\text{bos}, \text{chi}, \text{la}, \text{ny}, \text{sf}\}$

Assign Probabilities: $P[\{\text{bos}\}] = \frac{1}{3}$ $P[\{\text{chi}\}] = \frac{1}{6}$ $P[\{\text{la}\}] = \frac{1}{8}$

$$P[\{\text{ny}\}] = \frac{1}{8} \quad P[\{\text{sf}\}] = \frac{1}{4}$$



$W = \{\text{prefer west-coast city}\} = \{\text{la, sf}\}$

$$\begin{aligned} P[W] &= P[\{\text{la, sf}\}] = P[\{\text{la}\}] + P[\{\text{sf}\}] \\ &= \frac{1}{8} + \frac{1}{4} = \frac{3}{8} \end{aligned}$$