

Gaussian Vectors

- A **standard Gaussian random vector** is a random vector whose entries are independent Gaussian random variables with mean 0 and variance 1.

$$\underline{Z} = \begin{bmatrix} z_1 \\ \vdots \\ z_m \end{bmatrix}$$

where z_1, \dots, z_m are independent and z_i is Gaussian(0,1), $i=1, \dots, m$

Shorthand notation

$$\underline{Z} \sim N(\underline{0}, \mathbf{I})$$

- A **(jointly) Gaussian random vector** is a random vector that can be expressed as a linear transformation of a standard Gaussian random vector.

$$\underline{X} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

where $\underline{X} = \mathbf{A} \underline{Z} + \underline{b}$ for some standard Gaussian random vector \underline{Z} , matrix $\mathbf{A} \in \mathbb{R}^{n \times m}$, and vector $\underline{b} \in \mathbb{R}^n$.

→ Fully specified by its mean vector $\underline{\mu}_x = \mathbb{E}[\underline{X}]$ and covariance matrix $\Sigma_x = \mathbb{E}[(\underline{X} - \underline{\mu}_x)(\underline{X} - \underline{\mu}_x)^T]$.

• Some equivalent definitions: \underline{X} is a (jointly) Gaussian random vector if,

→ for any choice of vector $\underline{a} \in \mathbb{R}^n$, $\underline{a}^T \underline{X}$ is a scalar Gaussian random variable.

→ assuming that $\Sigma_{\underline{X}}$ is invertible, the joint PDF is

$$f_{\underline{X}}(\underline{x}) = \frac{1}{\sqrt{(2\pi)^n \det(\Sigma_{\underline{X}})}} \exp\left(-\frac{1}{2} (\underline{x} - \underline{\mu}_{\underline{X}})^T \Sigma_{\underline{X}}^{-1} (\underline{x} - \underline{\mu}_{\underline{X}})\right)$$

• Shorthand Notation: $\underline{X} \sim N(\underline{\mu}_{\underline{X}}, \Sigma_{\underline{X}})$

• Linear transformations of Gaussian random vectors are themselves Gaussian random vectors.

→ If $\underline{X} \sim N(\underline{\mu}_{\underline{X}}, \Sigma_{\underline{X}})$ and $\underline{Y} = \mathbf{B} \underline{X} + \underline{c}$,

then $\underline{Y} \sim N(\mathbf{B} \underline{\mu}_{\underline{X}} + \underline{c}, \mathbf{B} \Sigma_{\underline{X}} \mathbf{B}^T)$.

- Recall that jointly Gaussian random variables X and Y are independent if and only if $\text{Cov}[X, Y] = 0$.
- Similarly, the entries X_1, \dots, X_n of a jointly Gaussian vector \underline{X} are independent if and only if $\text{Cov}[X_i, X_j] = 0$ for all pairs $i \neq j$. This condition is equivalent to the requirement that the covariance matrix is

diagonal

$$\Sigma_{\underline{X}} = \begin{bmatrix} \text{Var}[X_1] & 0 & \dots & 0 \\ 0 & \text{Var}[X_2] & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \text{Var}[X_n] \end{bmatrix}$$

- One can also call X_1, \dots, X_n jointly Gaussian random variables if they satisfy the definition of a jointly Gaussian random vector when grouped into a vector.

• Example: \underline{X} is a Gaussian random vector with mean vector $\underline{\mu}_x = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ and covariance matrix

$$\underline{\Sigma}_x = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 2 \end{bmatrix}.$$

→ Let $\underline{Y} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \end{bmatrix} \underline{X} + \begin{bmatrix} 2 \\ -1 \end{bmatrix}$. Note that \underline{Y} is also a Gaussian random vector.

→ Determine the mean vector and covariance matrix of \underline{Y} .

Linearity of Expectation: $\underline{\mu}_y = \mathbf{A} \underline{\mu}_x + \underline{b}$ skipped calculation

$$= \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

Covariance Matrix of a Linear Transformation: $\underline{\Sigma}_y = \mathbf{A} \underline{\Sigma}_x \mathbf{A}^T$

$$\underline{\Sigma}_y = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix}$$

skipped calculation